

Data page I

We enter the village: measuring is suspended to « skip » the village.
At the end of the village, we're again behind same vehicle.
Measuring is restarted. Followed vehicle retains its neutral LV status

1 Data Page										L 2 S 4	Run # 1	SOURCE												
count of Oncoming LVs	mm.s	Km.xx	In Case Of... Pursuits		Sequence Type								S Suspect Subsections	In Case Of... Perturbations										
			Hare	Tortoise	Followed LV Information	A. Pursuit	B. Virtual Pursuit	C. Solo	D. LV Wait	E. Standstill	F. Skip	G. U-Turn		H. Break	Other Subsections and any comment	a. Weather	b. Built-Up Area	c. Roadblocks, Tolls, etc.	d. Works, Road Damages...	e. Congestion	f. Convoy	g. Others		
LV	0	0																						
LV III	3:18	5.0			R20	X																		
LV III	5:30	8.3					X																	
LV III	20:30	22.3		X	2CV	X																		
LV III	20:30	22.3							X															
LV II	22:50	24.8			4L	X																		
LV II	23:40	25.8			4L	X																		
LV II	26:50	29.8		X	4WD	X																		
LV III	26:50	29.8							X															
LV III	31:35	36.2																						
LV III	36:42	43.6			BMW	X																		
LV III	36:42	44.8			BMW	X																		
LV III																								

Caution: For mixed paved/unpaved sections, remember creating corresponding special subsections. And duly mention any incident that could affect the counter calibration (requiring a "break" sequence for performing precautionary calibration).

90 km/h
15 mn
S strange LV behaviour
LV stop
15 mn
same LV